Bring up report for Autocyplex.

# Orientation/System Overview

# Basic hardware Testing

## Illumination Profile

## 2.2 Resolution

## 2.3 Reflection

## 2.4 Invisislip vs water imaging comparison

## 2.5 Planar focal plane flatness

## 2.6 chromatic aberration

# Software

## Background Subtraction

Looking at line profile over a Na-K-ATPase stain line, we can see the background subtraction increased peak signal to bckgnd ratio from 1.32 to 2.25.

A screenshot of a computer

Description automatically generated

# Issues

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| **Problem ID** | **Problem Description** | **Solution** | **Date** | **Person** | **Status** |
| I1 | Core capture got stuck in random spot. No good leads on why. Previously driver in mm had crashed. Not the case here. I restarted image acquisition and it had no issue. For reference, it had captured bleached cycle 1, stain/bleach for cycle 2 and stalled at stained for cycle 3. | No good proposed solution. Idea could be to see if core capture is taking too long and literally asking it to take it again. | 11/29/23 | MA | No resolution |
| F1 | Pressure source loud and unable to sustain pressure >600mBar. | Contacted Elveflow to get exchange. Most likely pump is failing. | 11/28/23 | MA | In email exchanges right now. |
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# Solution Testing

## F1

Pump is mega loud. Record 85db on phone and documents say should be 53db. Performance was not hindered until recently. As of now, it is only able to sustain 600mBar pressure. Solution is to do exchange with Elveflow for new unit as this one is clearly failing.

## I1

Really hard to say here. It is beyond my abilities to resolve an issue with the core capture stalling out if it is due to architecture. Simply restarting the program made it work though. A possible solution could be to make the capture function wait a bit. If it exceeds a certain time frame, it simply asks it to do it again. Python IDE gave no errors back in this case. It just didn’t proceed on in the code.

Other possible solutions could be to alternative code to capture image. No need to use mm core capture. I could use python package from photometric to capture as well. Its untested if both forms of capturing can be done at the same time or if mm called ‘dibs’ on the camera.